

Nonlinear Equalization for Optical Communications

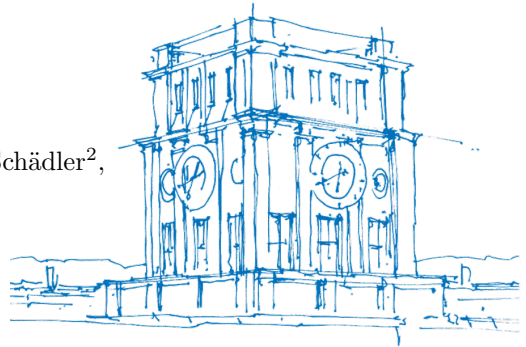
Based on Entropy-Regularized Mean Square Error

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TUM Uhrenturm

Outline

- **Motivation:**

- ▶ Nonlinear impairments in optical communications.
- ⇒ Cost functions for nonlinear equalization are required.

- **Contribution:**

- ▶ New cost function for nonlinear equalization.

F. Diedolo, G. Böcherer, M. Schädler, *et al.*, *Nonlinear equalization for optical communications based on entropy-regularized mean square error*, submitted to ECOC, 2022. [Online]. Available:

<https://arxiv.org/abs/2206.01004>

Outline

Motivation

Contribution

Conclusions

Cost Functions for Nonlinear Equalizers

- Compensation of component non-linearities critical in short-reach optics.
- Two cost functions popular in ML and applied in optics:

MSE¹² Mean Squared Error

CE³⁴ Cross Entropy

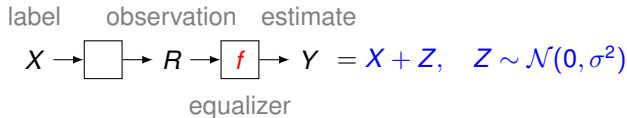
¹S. Zhang, F. Yaman, K. Nakamura, *et al.*, “Field and lab experimental demonstration of nonlinear impairment compensation using neural networks,” *Nat. Commun.*, 2019.

²P. J. Freire, V. Neskornuik, A. Napoli, *et al.*, “Complex-valued neural network design for mitigation of signal distortions in optical links,” *J. Light. Technol.*, 2021.

³M. Schädler, G. Böcherer, and S. Pachnicke, “Soft-demapping for short reach optical communication: A comparison of deep neural networks and volterra series,” *J. Light. Technol.*, 2021.

⁴S. Deligiannidis, A. Bogris, C. Mesaritakis, *et al.*, “Compensation of fiber nonlinearities in digital coherent systems leveraging long short-term memory neural networks,” *J. Light. Technol.*, 2020.

Mean Square Error: Suitable for Nonlinear Equalizers?



- Mean square error: $|X - f(R)|^2$.
- Cross-entropy: $-\log Q_{X|Y}(X|f(R))$.
- **Their Claim:**⁵ if $Y = X + Z$ with Gaussian Z :

$$\boxed{\text{MSE} \equiv \text{CE}}$$

- **Our Claim:** this statement is wrong!
- How did the authors arrive at this claim?

⁵Section II.A, P. J. Freire, J. E. Prilepsky, Y. Osadchuk, *et al.*, “Neural networks based post-equalization in coherent optical systems: Regression versus classification,” *arXiv*, 2021. [Online]. Available: <https://arxiv.org/abs/2109.13843v3>

Advanced convolutional **neural networks** for nonlinearity mitigation in long-haul WDM transmission systems

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... M. Kamalian-Kopae, I.S. Chakhovskoy, S.K. Turitsyn - Scientific Reports, 2021 - nature.com
 ... **Net** as compared to the conventional numerical NFT methods becomes evident when we deal with noise-corrupted signals, where the **neural networks** ... we train the **neural network** on the ...
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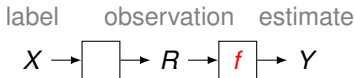
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... A. Napoli, M. Kamalian-Kopae, S.K. Turitsyn - arXiv preprint arXiv ... 2021 - arxiv.org
 We quantify the achievable reduction of the processing complexity of artificial **neural network**-based equalizers in a coherent optical channel using the pruning and quantization ...
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Neural networks based post-equalization in coherent optical systems: regression versus classification

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 In this paper, we address the question of which type of predictive modeling, classification, or regression, fits better the task of equalization using **neural networks** (NN) based post-...
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Likelihood Versus Posterior Probability



Conditional Log-Likelihood and Mean Squared Error⁶

- Assume

$$X = Y + Z, \quad Z \sim \mathcal{N}(0, \sigma^2)$$

- Cross-entropy is then

$$-\log Q_{X|Y}(X|f(R)) = \log \sqrt{2\pi\sigma^2} + \frac{|X - f(R)|^2}{2\sigma^2} \log e$$

- Obviously,

$$\boxed{\text{MSE} \equiv \text{CE}}.$$

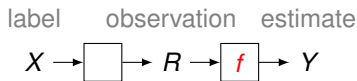
Clash of terminology:

	Communications	Goodfellow (2016) Section 5.5.1
$Q_{X Y}$	posterior	likelihood
$Q_{Y X}$	likelihood	

⇒ Supposedly, the author's⁵ claim is based on confusing the posterior $Q_{X|Y}(\cdot|y)$ being Gaussian with the likelihood $Q_{Y|X}(\cdot|x)$ being Gaussian.

⁶Section 5.5.1 of I. Goodfellow, Y. Bengio, and A. Courville, *Deep learning*. MIT press, 2016

When $MSE \equiv CE$



- Suppose

$$Y = X + Z$$

with Z **and** X independent Gaussian.

⇒ The posterior $Q_{X|Y}(\cdot|y)$ is Gaussian⁷.

⇒ In this case⁸

$$\boxed{MSE \equiv CE}$$

Consequences

- Information theory often assumes Gaussian inputs, and in this case $MSE \equiv CE$.
- When X and Y are oversampled, the assumption $Q_{X|Y}$ being Gaussian may not be that bad, which explains why MSE works well in this case.
- When X and Y are multiplexed digital subcarrier signals, X is pretty much Gaussian and MSE works well on the multiplexed signals.

In the following, we consider practically relevant 1 sample per symbol (SPS) signals. As we will see, $MSE \not\equiv CE$.

⁴[8, Sec. 3.5] R. G. Gallager, *Stochastic processes: theory for applications*. Cambridge University Press, 2013

⁵[8, Sec. 10.7]

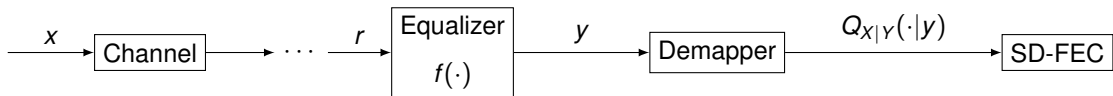
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Channel Model



The transmit symbols x are drawn from a finite alphabet \mathcal{X} , e.g., QAM, ASK.

Most systems use binary FEC and the demapper output is a log-likelihood ratio (LLR)

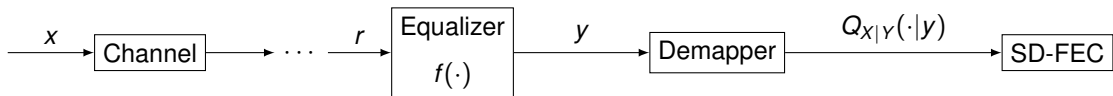
$$\ell_i = \log \frac{Q_{B_i|Y}(0|y)}{Q_{B_i|Y}(1|y)},$$

which can be calculated from $Q_{X|Y}$ through

$$Q_{B_i|Y}(b|y) = \sum_{x \in \mathcal{X}_i^b} Q_{X|Y}(x|y),$$

where \mathcal{X}_i^b is the set of constellation points with the i -th label bit equal to b , $b \in \{0, 1\}$.

Design Criterion for SD-FEC



An achievable information rate (AIR) of a system with demapper $Q_{X|Y}$ is^{9,10}

$$[H(X) - \mathbb{E}[-\log Q_{X|Y}(X|Y)]]^+$$

As the input entropy $H(X)$ does not depend on the receiver, the design problem can be rephrased as

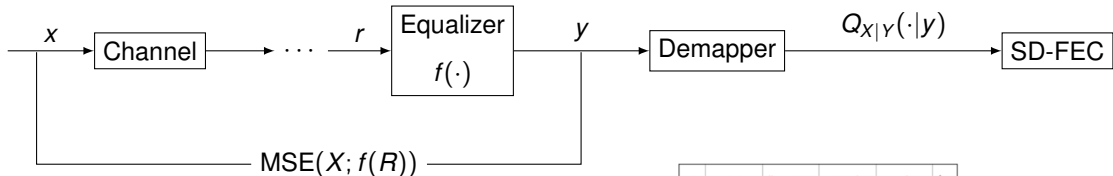
$$\underset{\text{Equalizer, Demapper}}{\text{minimize}} \quad \mathbb{E}[-\log Q_{X|Y}(X|Y)]$$

⁹N. Merhav, G. Kaplan, A. Lapidoth, *et al.*, "On information rates for mismatched decoders," *IEEE Trans. Inf. Theory*, 1994.

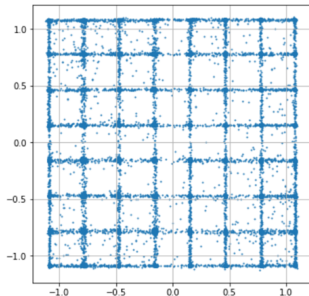
¹⁰G. Böcherer, P. Schulte, and F. Steiner, "Probabilistic shaping and forward error correction for fiber-optic communication systems," *J. Light. Technol.*, 2019.

MSE Training

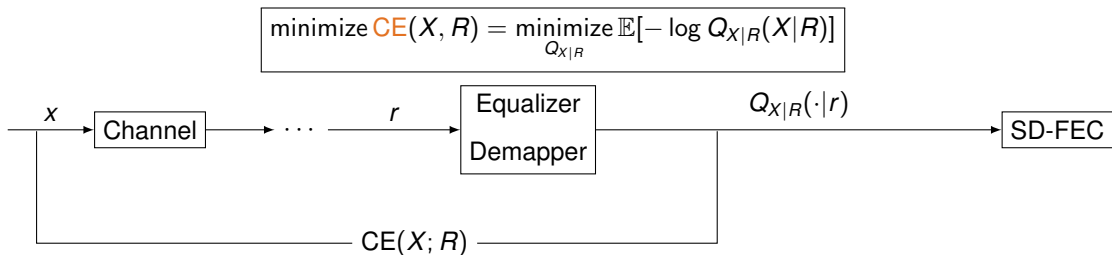
$$\text{minimize } \text{MSE}(X, f(R)) = \text{minimize}_f \mathbb{E}[|f(R) - X|^2]$$



- It minimizes the pre-FEC bit error rate (BER)
- Does not maximize the AIR
- Hence suboptimal for SD-FEC systems



CE Training



- It maximizes the AIR
- The trained device acts as an equalizer and demapper jointly
- Some algorithms, e.g. carrier and timing recovery, need access to the equalized signal which is lost

A New Cost Function

We wish to find a cost function which

- Maximizes the AIR for SD-FEC systems
- Achieves same pre-FEC BER as MSE cost function
- Preserves the block structure and the access to an equalized signal

Entropy-Regularized MSE (I)

Our approach consists in optimizing the equalizer based on the demapper output

$$\underset{f}{\text{minimize}} \quad \mathbb{E}[-\log Q_{X|Y}(X|f(R))]$$

where we choose the **AWGN demapper**

$$Q_{X|Y}(x|y) = \frac{P_X(x)Q_{Y|X}(y|x)}{Q_Y(y)}$$

where P_X is the input distribution and

$$Q_{Y|X}(y|x) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{(y-x)^2}{2\sigma^2}\right]$$

is a Gaussian channel and

$$Q_Y(y) = \sum_{x' \in \mathcal{X}} P_X(x')Q_{Y|X}(y|x').$$

Note that $x \in \mathcal{X}$ and the demapper parameters are σ^2 and \mathcal{X} .

Entropy-Regularized MSE (II)

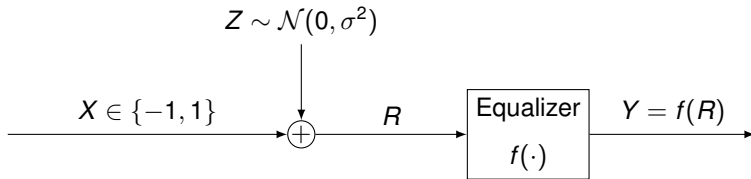
Now, we solve the optimization problem

$$\begin{aligned}
 \arg \min_f \mathbb{E}[-\log Q_{X|Y}(X|f(R))] &= \arg \min_f \mathbb{E} \left[-\log \frac{P_X(X)Q_{Y|X}(f(R)|X)}{Q_Y(f(R))} \right] \\
 &= \arg \min_f \mathbb{E} \left[-\log \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{|f(R)-X|^2}{2\sigma^2}} \right] + \mathbb{E}[-\log P_X(X)] - \mathbb{E}[-\log Q_Y(Y)] \\
 &= \arg \min_f \frac{1}{2} \log(2\pi\sigma^2) + \frac{\log e}{2\sigma^2} \mathbb{E}[|f(R) - X|^2] + h(X) - \mathbb{E}[-\log Q_Y(f(R))]
 \end{aligned}$$

After dropping all the terms which do not depend on f the optimization problem is reduced to

$$\begin{aligned}
 \arg \min_f \underbrace{\mathbb{E}[|f(R) - X|^2]}_{\text{MSE}(X, f(R))} - \underbrace{2\sigma^2 \mathbb{E}[-\log Q_Y(f(R))]}_{\text{Entropy regularization}} \\
 = \arg \min_f \text{MSE-X}(X, f(R))
 \end{aligned}$$

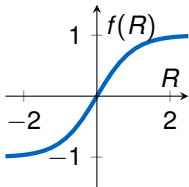
BPSK Toy Example [11]



MSE

$$\arg \min_f \mathbb{E}[|f(R) - X|^2]$$

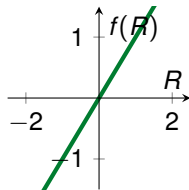
$$f^*(R) = \tanh(R)$$



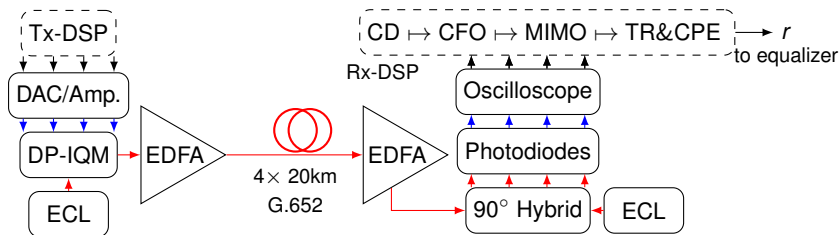
MSE-X

$$\arg \min_f \mathbb{E}[|f(R) - X|^2] - 2\sigma^2 \mathbb{E}[-\log Q_Y(f(R))]$$

$$f^*(R) = R$$



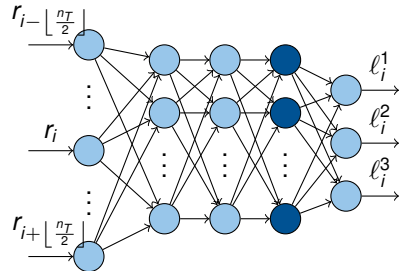
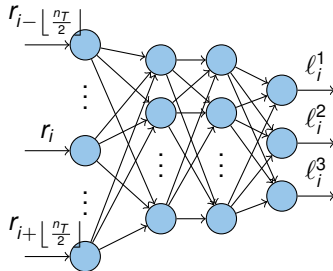
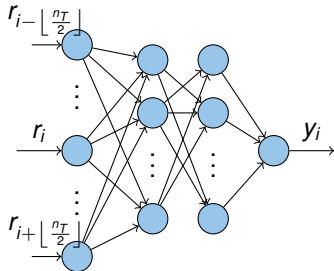
Experimental Setup



- 80 GBd DP-64QAM transmitted signal with gross data rate of 960 Gb/s and net rate 800 Gb/s
- CAZAC training sequence for frame and carrier frequency synchronization, and channel estimation.
- Four 120GSa/s digital-to-analog converters (DACs) generate an electrical signal amplified by four 60GHz 3dB-bandwidth amplifiers.
- A tunable 100kHz external cavity laser (ECL) generates a continuous wave that is modulated by a 32GHz 3dB-bandwidth DP-I/Q modulator.
- The receiver has an optical 90°-hybrid and four 100GHz balanced photodiodes
- E/O conversion by an oscilloscope with 256GSa/s and 110GHz 3dB-bandwidth.

Neural Networks Structure

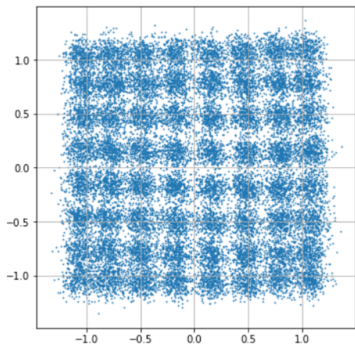
Structure	Cost function	Name	Activation
17 32 26 1	MSE, MSE-X	NN _{eq}	ReLU
17 32 26 3	BCE	NN _{joint} ¹	ReLU
17 32 26 16 3	BCE	NN _{joint} ²	ReLU



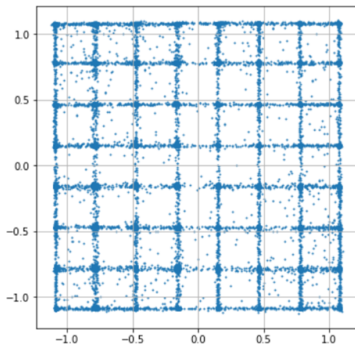
Note: NN_{eq} is followed by the demapper. The parameters σ^2 and \mathcal{X} are left constant during training, then learned from the equalized train data, then fixed and applied to the test data.

Constellation Plot

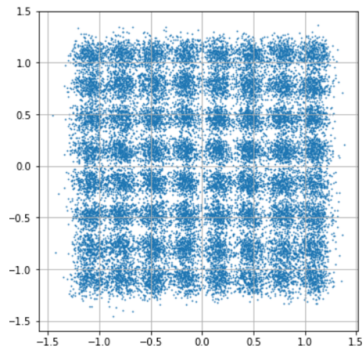
Constellation before equalizer



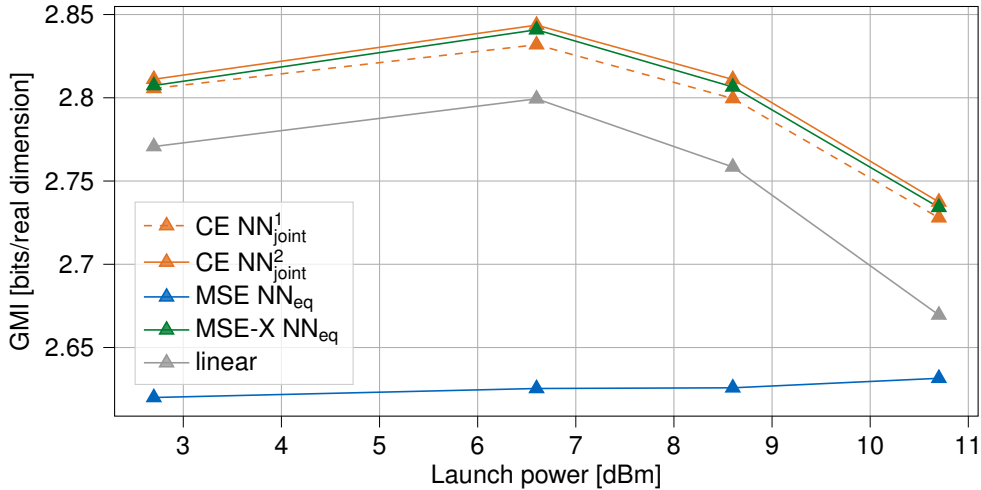
Constellation after MSE equalizer



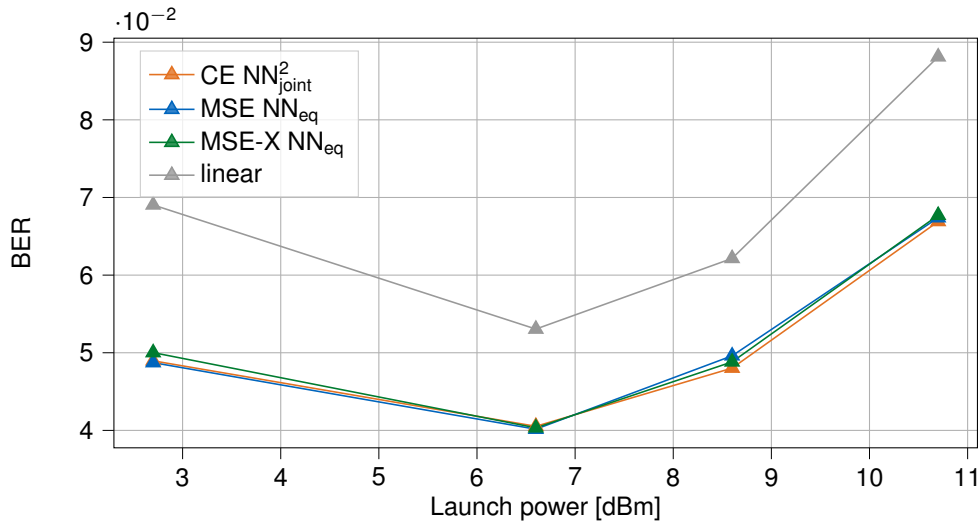
Constellation after MSE-X equalizer



Experimental Results - GMI



Experimental Results - BER



Volterra Nonlinear Equalization

- Linear FIR filter: use n_T taps $\mathcal{X}_1 = \{r_{i-\lfloor \frac{n_T}{2} \rfloor}, \dots, r_i, \dots, r_{i+\lfloor \frac{n_T}{2} \rfloor}\}$
- This corresponds to order 1:

$$\mathcal{F}_1 = \{a: a \in \mathcal{X}_1\} = \mathcal{X}_1$$

- Volterra equalizer adds higher orders:

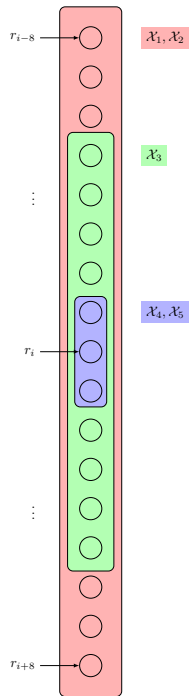
$$\mathcal{F}_2 = \{a \cdot b: a, b \in \mathcal{X}_2\}$$

$$\mathcal{F}_3 = \{a \cdot b \cdot c: a, b, c \in \mathcal{X}_3\}$$

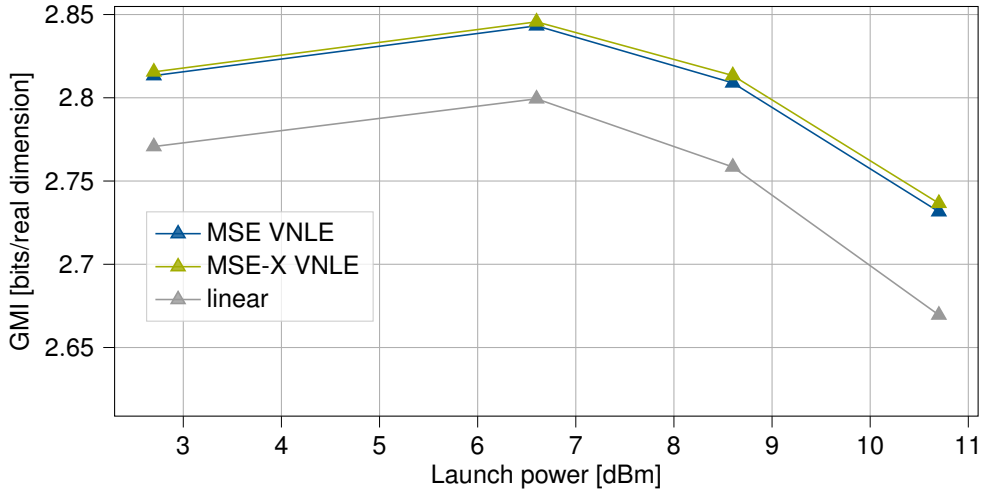
⋮

$$\mathcal{F}_k = \{a_1 \cdot a_2 \cdot \dots \cdot a_k: a_1, \dots, a_k \in \mathcal{X}_k\}$$

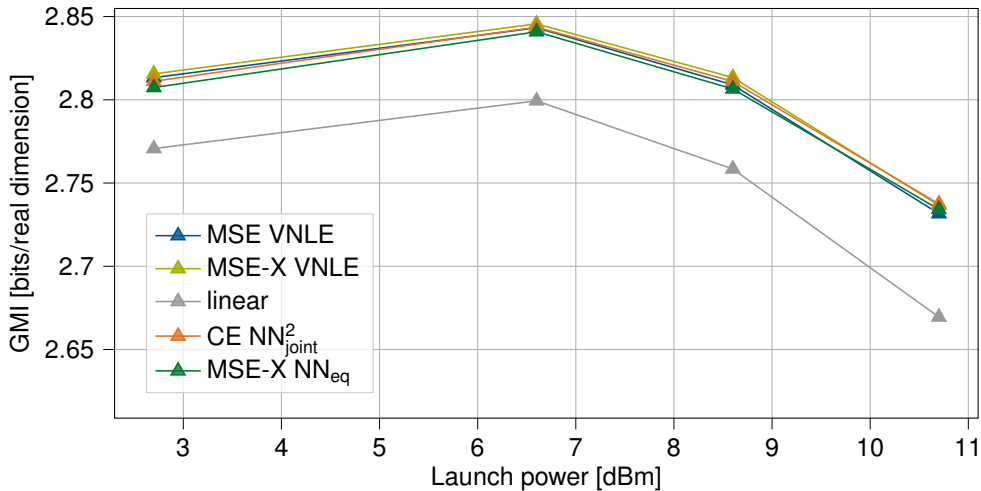
- The features $\mathcal{F}_1, \dots, \mathcal{F}_k$ are inputs to a linear FIR filter.
- The linear FIR filter has $|\mathcal{F}_1| + \dots + |\mathcal{F}_k|$ taps.
- Our Volterra equalizer specified to the right has 492 taps.



Experimental Results - VNLE



Experimental Results - Comparison



Outline

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Summary and Future Work

Summary:

- MSE cost function is suboptimal for SD-FEC systems
- CE training causes the loss of the equalized signal, useful for DSP algorithms
- We proposed a new objective to train nonlinear equalizers:

$$\text{MSE-X}(f(R), X) = \mathbb{E}[|f(R) - X|^2] - 2\sigma^2 \mathbb{E}[-\log Q_Y(f(R))]$$

- We tested the cost function on experimental data and show compatibility with VNLE

Future work:

- Test on IM-DD systems
- Optimize the demapper parameters:
 - ▶ Noise power parameter σ^2
 - ▶ Target constellation \mathcal{X}
- Nonlinear equalization for multicarrier systems

References I

- [1] F. Diedolo, G. Böcherer, M. Schädler, and S. Calabrò, *Nonlinear equalization for optical communications based on entropy-regularized mean square error*, submitted to ECOC, 2022. [Online]. Available: <https://arxiv.org/abs/2206.01004>.
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